



Introduction

Multiple Learning Systems

- Computations in the brain are efficient, but energy consumption is high in deep neural networks
- The brain consists of hierarchically structured multiple learning systems, which manage episodic and statistical learning
 - Monosynaptic pathway (MSP): statistical, overlapping, slow learning
 - Trisynaptic pathway (TSP): episodic, sparse, fast learning
- It is unclear how the brain arrives at multiple learning systems. What gives rise to these?

Meta-Learning

- Colloquially known as “learning to learn”
- Humans learn new concepts very efficiently. Is it possible for machines to do the same?
- Continual learning — where a model is fed a large stream of data needs to learn without forgetting — is difficult due to catastrophic forgetting or interference
 - A replay buffer and sparse representations can help

Proposal

- Meta-learn parameters m (modulates within-layer k-winners-take-all) & LR (per-layer learning rate)

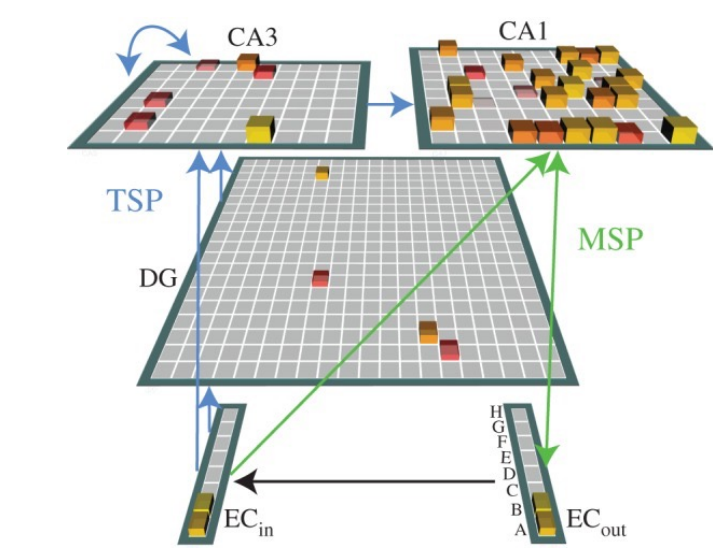


Figure 1. A deep neural network of the MSP and TSP. Adapted from “Complementary Learning Systems within the Hippocampus: A Neural Network Modelling Approach to Reconciling Episodic Memory with Statistical Learning”, Schapiro et al., 2017.

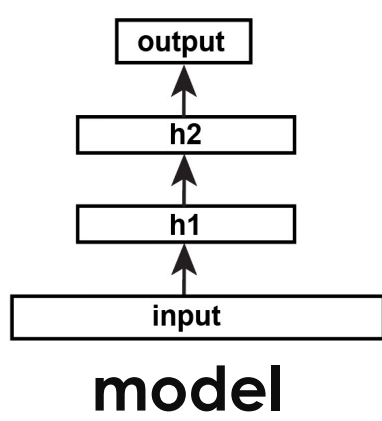


Figure 2. Our initial proposed meta-learned model.

Methods

1. Initial baselines

- Base code off La-MAML, a continual online meta-learning model with a small replay buffer of examples from the past
- Bi-level optimization: outer (meta) loss which updates hyperparameters, and inner loss (traditional optimization)
- Train on 20 MNIST rotation tasks, each a 10-way classification
- Analyze sparse representations of weights and biases, unit variance of hidden layers

2. K-winners-take-all & per-layer learning rate

- Induce sparsity/inhibition in each layer through a meta-learned continuous multiplier; top k neurons are active
- Learn per-layer learning rates to mirror pathways in the brain

3. Various architectures

- 2-layer
- 4-layer
- 4-layer skip two-path; mimics two learning pathways
- 4-layer split two-path; mimics two learning pathways

4. New tasks and datasets

- Use task incremental learning instead of class incremental learning
- Add a set or individual label to each image; have model identify both image and label
- Test on MNIST permutations and CIFAR datasets (real world images)



Figure 3. A subset of the MNIST rotation dataset. Each digit (0-9) has 20 different angles of rotation.

$$a^* = [a - I]_+$$

$$I = \text{descending-sort}([a]_+)(k_{i+1})$$

$$k_i = \max(k_{\text{target}}, [k_{\text{max}} - E_i(k_{\text{max}} - k_{\text{target}})]/\sigma)$$

$$a^* = [a - I]_+$$

$$I = \text{descending-sort}([a]_+)(k_{i+1})$$

$$I = m * I$$

Figure 4. a) Traditional k-wins implementation. b) Our modification, with a meta-learned continuous multiplier m .

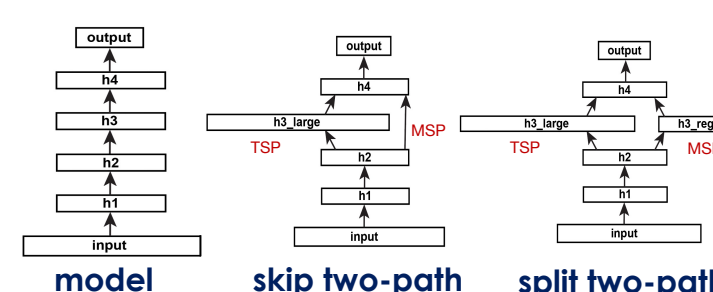


Figure 5. a) A 4-layer model. b) A skip two-path cortical-hippocampal architecture with a large h3 layer. c) A split two-path cortical-hippocampal architecture with two options for h3 layer size.

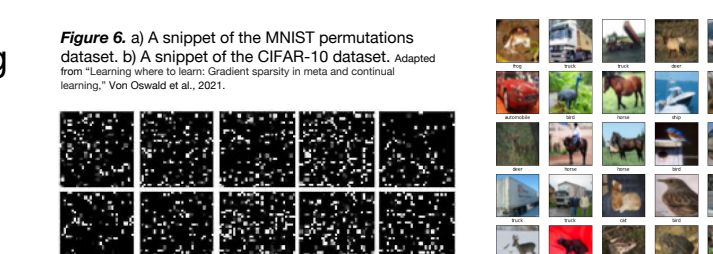


Figure 6. a) A snippet of the MNIST permutations dataset. b) A snippet of the CIFAR-100 dataset. c) A snippet of the CIFAR-100 dataset with individual labels.

Results

Figure 7. In a 2-layer network, meta-learning the inhibition multiplier m and learning rate LR leads to a, b) efficient task representations and c) benefits ANN performance.

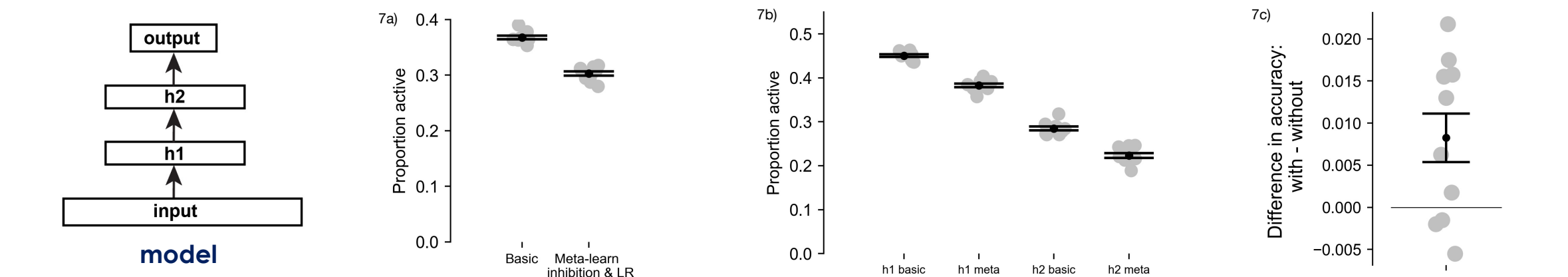


Figure 8. In a meta-learned 2-layer network, hierarchically structured a) sparsity and b) learning rates emerge.

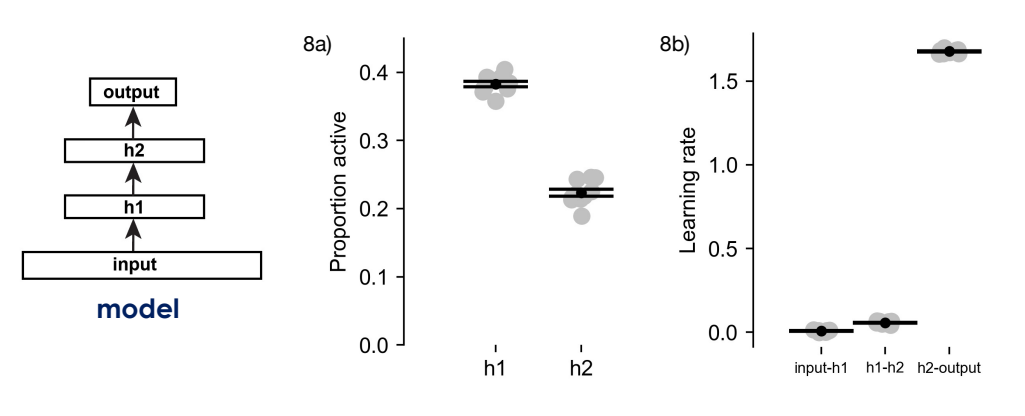


Figure 9. In a deeper 4-layer network, similar patterns of a) sparsity and b) learning rate are achieved through meta learning.

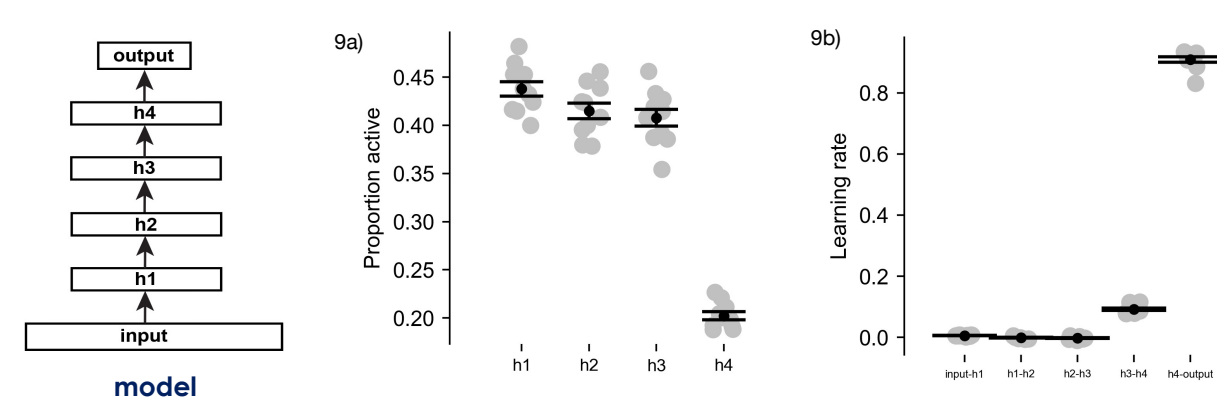


Figure 10. In the skip two-path architecture, the large intermediate layer $h3_large$ becomes sparser over tasks through meta-learning and remains sparser of all layers. a) Average sparsity for all layers. b) Sparsity over task index.

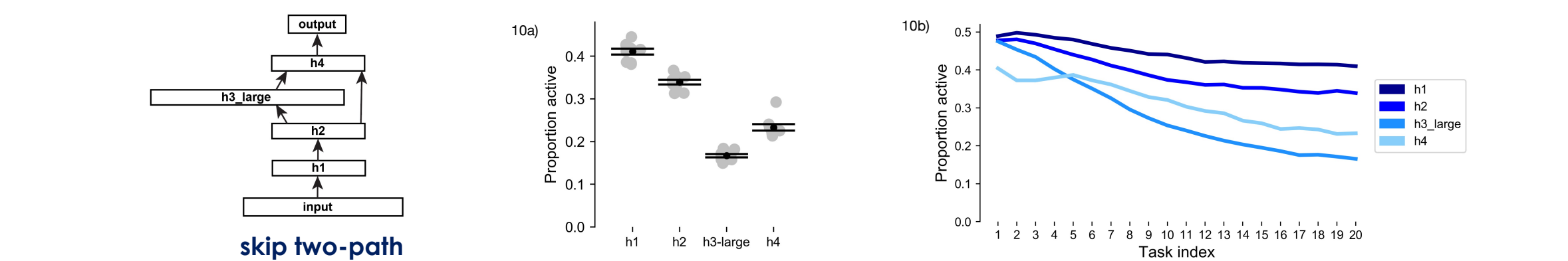


Figure 11. In the skip two-path architecture, higher learning rates for the large intermediate layer $h3_large$ emerge through meta-learning. a) Average LR for all layers. b) Average LR for all layers except for the last. c) LR over task index.

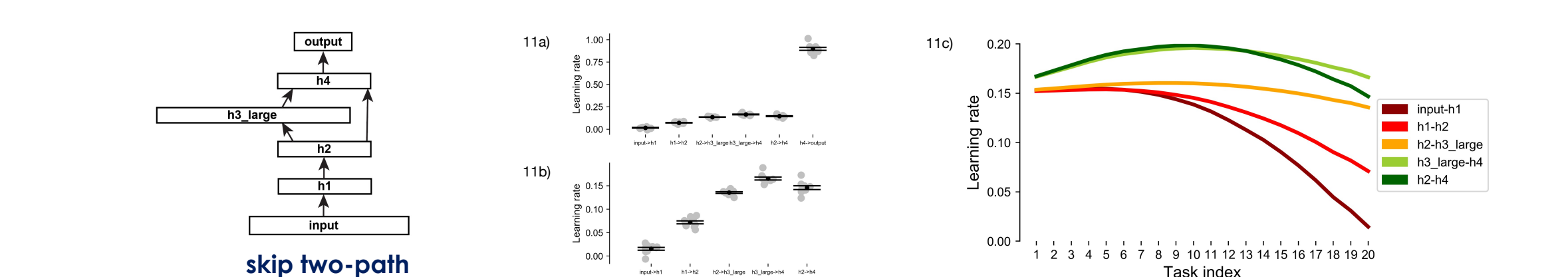


Figure 12. In the split two-path architecture, $h3_large$ exhibits a higher level of sparsity than $h3_regular$ and becomes increasingly sparse through meta-learning. a) Average sparsity for all layers. b) Sparsity of task index.

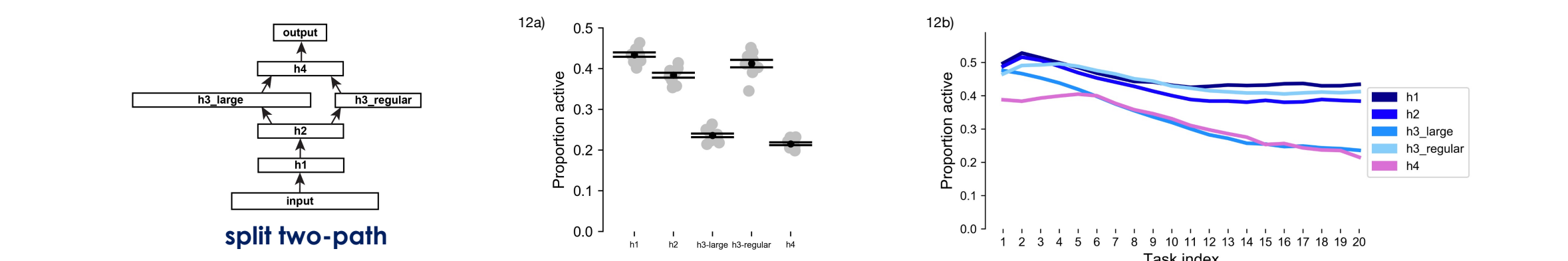


Figure 13. In the split two-path architecture, $h3_large$ decorrelates task representations more than $h3_regular$, similar to the TSP vs. MSP.

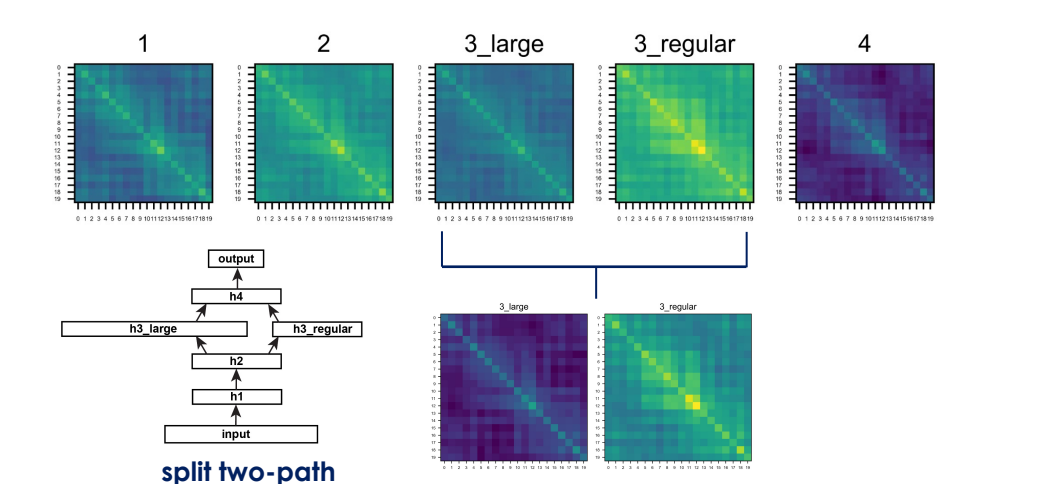
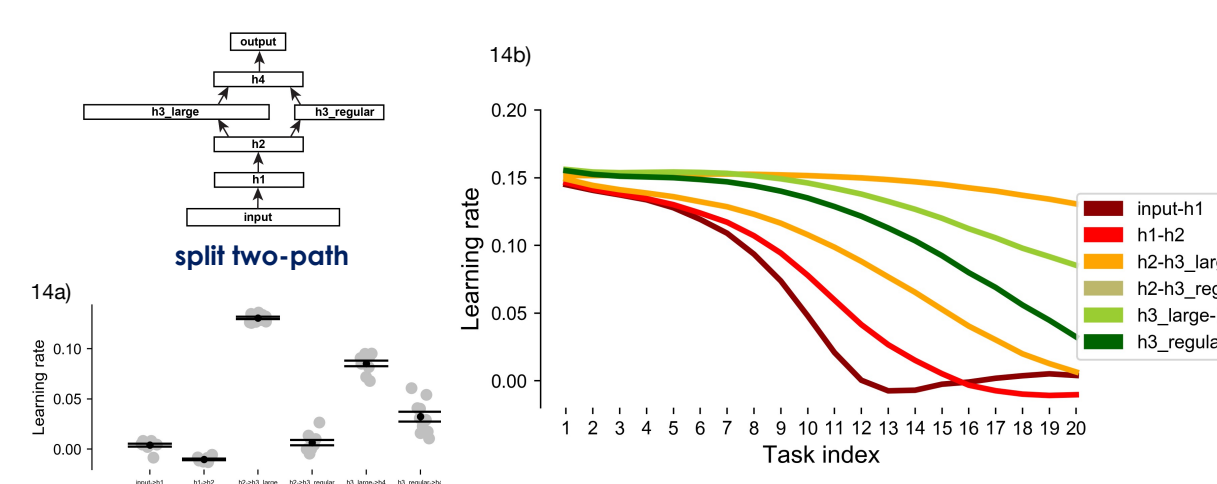


Figure 14. In the split two-path architecture, $h3_large$ learns more rapidly than $h3_regular$ through meta-learning. a) Average LR for all layers. b) LR over task index.



Conclusions

A Brain-like Model

- Meta-learning parameters that modulate interference and learning results in efficient, sparse task representations
- Resulting architecture shows a hierarchal differentiation of sparsity and learning rates that resembles the brain!
 - MSP vs. TSP
 - Hippocampus vs. neocortex

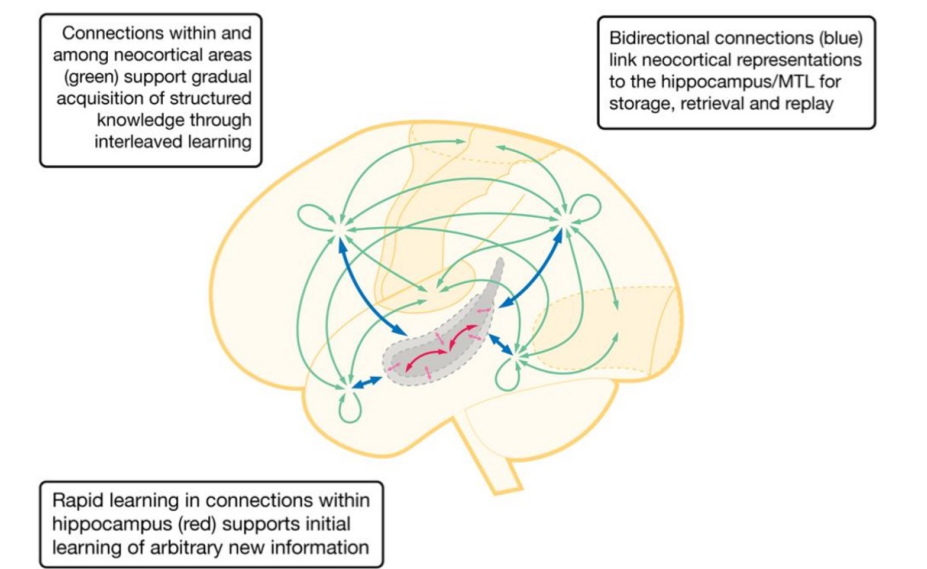


Figure 15. Hippocampal-cortical interactions with both rapid and gradual learning, of which the complementary learning systems within the hippocampus are a microcosm. Adapted from “What Learning Systems do Intelligent Agents Need? Complementary Learning Systems Theory Updated”, Kumar et al., 2016.

Future Questions

- Is sparsity (% neurons active) dependent on the size of the layer?
- Why is learning rate generally highest in projections to the last layer?
- Is it possible to learn the optimal architecture of a model, including number of layers, size of layers, and pathway projections?
- Will meta-learning these parameters result in similar patterns and performance on real world images?
- Are there sparse representations in the widely used CNN and transformer (e.g., Chat GPT) models?

Broader Implications

- This work provides a general framework for neural architectures in the brain, such as:
 - Visual and auditory processing systems
 - Grid and place cell (spatial navigation) systems
 - Hippocampal-neocortical learning during sleep
- Few-shot and reinforcement learning, as well as natural language processing, can be optimized with meta-learning methods

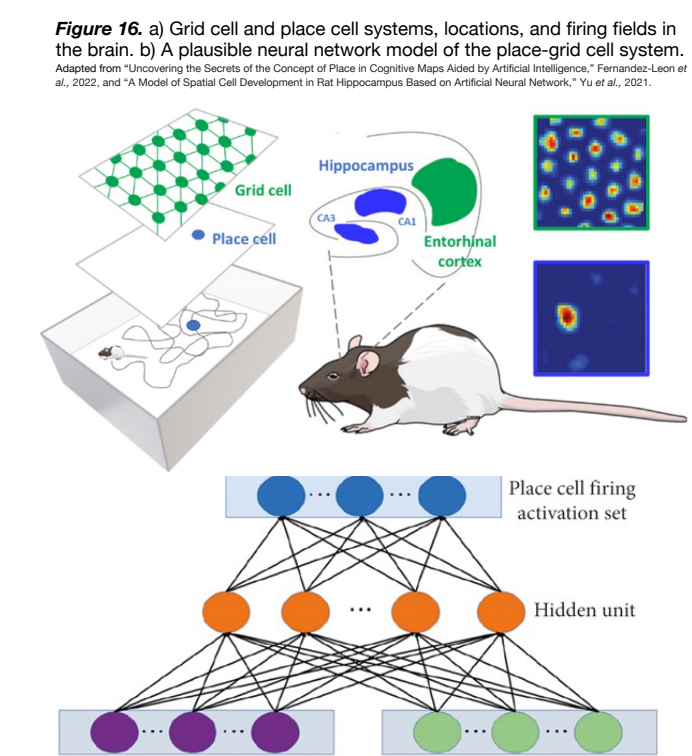


Figure 16. a) Grid cell and place cell systems, locations, and firing fields in the brain. b) A plausible neural network model of the place-grid cell system. Adapted from “What Learning Systems do Intelligent Agents Need? Complementary Learning Systems Theory Updated”, Kumar et al., 2016.

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